

On-Line Trajectory Generation In Robotic Systems: Basic Concepts For Instantaneous Reactions To Unforeseen (Sensor) Events (Springer Tracts In Advanced Robotics) By Torsten Kröger

By Torsten Kröger

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Towards Online Trajectory Generation Considering Robot Dynamics and Torque Limits a previous work on online trajectory generation as a basis, this

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The robot has to react on sensor events The figure illustrates a simple case for third-order on-line trajectory generation with and without synchronization
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